Feasibility of in vivo image-guided navigation during robotic sentinel node removal

Published: 17-08-2021 Last updated: 04-04-2025

The purpose of the study is to test the feasibility of image-guided navigation during robotassisted sentinel node dissection.

Ethical review Approved WMO **Status** Recruiting **Health condition type** Other condition

Study type Observational invasive

Summary

ID

NL-OMON54304

Source

ToetsingOnline

Brief title

Image-guided navigation during robotic sentinel node removal

Condition

Other condition

Synonym

Sentinel node metastasis

Health condition

surgical and medical procedures - sentinel node dissection

Research involving

Human

Sponsors and support

Primary sponsor: Antoni van Leeuwenhoek Ziekenhuis

Source(s) of monetary or material Support: Ministerie van OC&W

Intervention

Keyword: Image-guided navigation, Robot-assisted sentinel node removal, Sentinel node dissection

Outcome measures

Primary outcome

The main study endpoint is the feasibility of electromagnetic navigation during robot-assisted sentinel node dissection.

Electromagnetic navigation is considered feasible if in 75% of the sentinel node procedures the technology can be applied successfully.

In order to quantify the primary study parameter the percentage of successfully removed sentinel nodes will be taken into account. Success is defined when a sentinel node is correctly localized with navigation and perioperative validated with the gamma probe. Failure of using the navigation per sentinel node would be either not removing a target sentinel node or removing per-operatively incorrectly identified target sentinel node.

Secondary outcome

The first secondary study parameter is the time to localize and remove the sentinel node, together with the added time to surgery due to deploying navigation. The SUS-score will be used to evaluate the usability of the navigation within the surgery. The last study parameter will be the evaluation of the sentinel node size versus the success rate.

Study description

Background summary

Image-guided navigation surgery allows for full utilization of pre-operative imaging during open surgery, and has the potential of reducing both irradical resections and morbidity. Rapid extension of robot-assisted surgery has increased the need for robot-compliant image-guided techniques. This is the first feasibility study towards clinical implementation of the navigation setup into robot-assisted image-guided navigation surgery.

Study objective

The purpose of the study is to test the feasibility of image-guided navigation during robot-assisted sentinel node dissection.

Study design

Investigator initiated, prospective, non-randomized, feasibility study

Study burden and risks

The burden due to participation in the study is limited to an intra-operative CBCT scan, an US scan and prolonged surgery time (about 15 minutes for the CBCT or 5 minutes for the US). Only for the first 25 patients, due to the CBCT scan the patient will be exposed to some radiation (4 mSv). The risks associated with the extended operation time are considered limited, taking into account the duration of the operation.

No extra visits or interventions are associated with inclusion in the study. The surgical intervention will not be different from a routine robot-assisted sentinel node dissection.

Contacts

Public

Antoni van Leeuwenhoek Ziekenhuis

Plesmanlaan 121 Amsterdam 1066CX NL

Scientific

Antoni van Leeuwenhoek Ziekenhuis

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Trial sites

Listed location countries

Netherlands

Eligibility criteria

Age

Adults (18-64 years) Elderly (65 years and older)

Inclusion criteria

- Scheduled for abdominal robotic sentinel node resection
- >= 18 years old
- Provided written *informed consent*
- SN should be fixed relative to retroperitoneal structures or major vessels

Exclusion criteria

- Metal hip implants / implants in the pelvic area
- Pacemaker, defibrillator

Study design

Design

Study type: Observational invasive

Masking: Open (masking not used)

Control: Uncontrolled

Primary purpose: Treatment

Recruitment

NL

Recruitment status: Recruiting
Start date (anticipated): 02-03-2022

Enrollment: 55

Type: Actual

Medical products/devices used

Generic name: Image-guided navigation setup

Registration: No

Ethics review

Approved WMO

Date: 17-08-2021

Application type: First submission

Review commission: METC NedMec

Approved WMO

Date: 17-08-2022

Application type: Amendment

Review commission: METC NedMec

Approved WMO

Date: 18-04-2023

Application type: Amendment

Review commission: METC NedMec

Approved WMO

Date: 04-03-2025

Application type: Amendment

Review commission: METC NedMec

Study registrations

Followed up by the following (possibly more current) registration

No registrations found.

Other (possibly less up-to-date) registrations in this register

No registrations found.

In other registers

Register ID

CCMO NL77462.031.21